

When Distributed Computation is Communication Expensive

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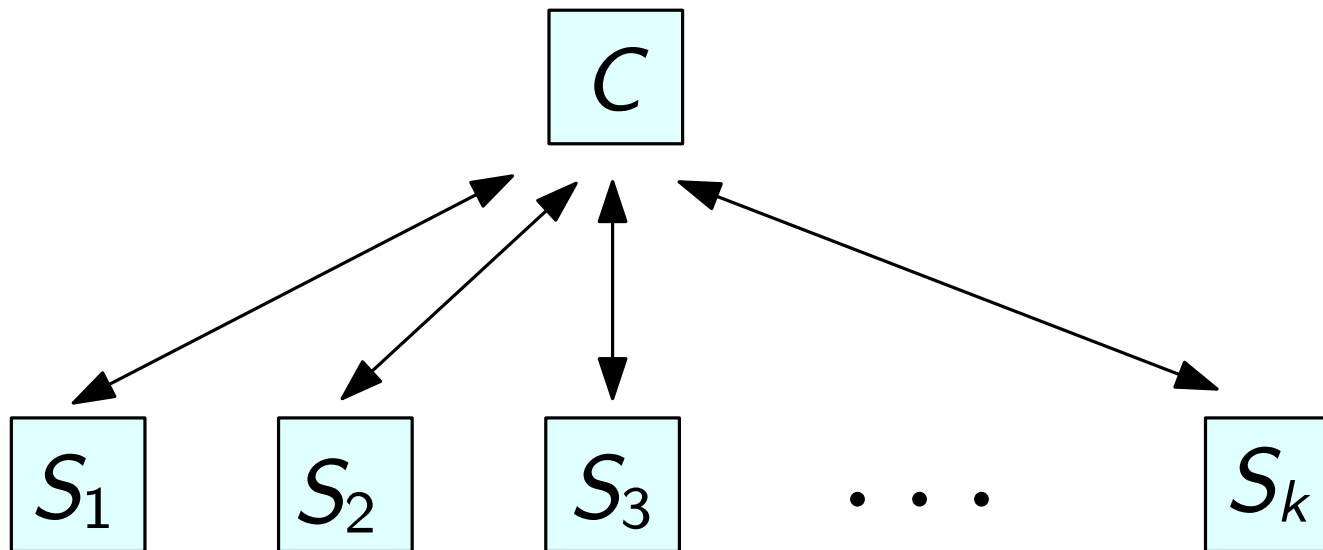
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DISC'13,
October, 2013

The coordinator model

- **The coordinator model:** We have k machines (sites) and one central server.
 - Each site has a 2-way communication channel with the server.
 - Each site has a piece of data $x_i (i \in [k])$.
 - Goal is to compute $f(x_1, \dots, x_i)$ together via communication, for some function f .



Motivation

Communication → energy, bandwidth, ...



Sensor networks



Data in the cloud

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Abstraction



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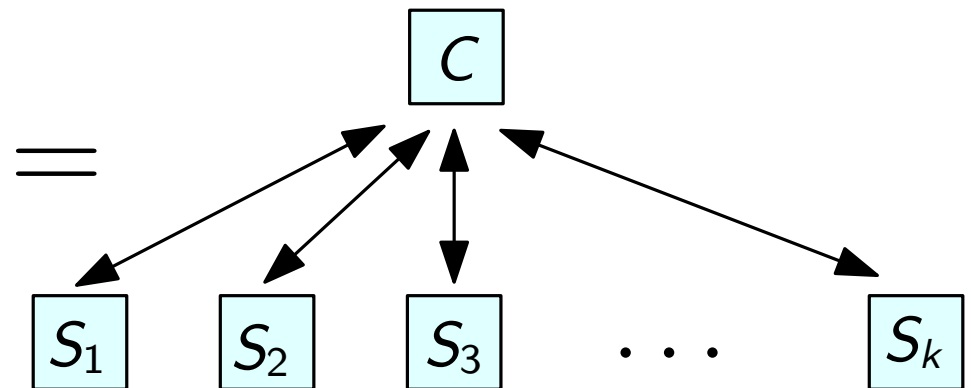
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Data in the cloud

Sensor networks

Abstraction



Conceptual messages

If we want communication efficient protocols, then for many problems/functions f ,

- **Allow an approximate solution.**
 - For a problem whose output is a single numerical value x , approximation means outputting $\tilde{x} \in [(1 - \epsilon)x, (1 + \epsilon)x]$.
 - For a problem whose output is YES/NO, approximation means outputting YES if the input is close to have the property, and NO otherwise.
- **Use well-designed input layouts.**
- **Explore prior distributional properties of the input dataset.**

Our results

Problem	With duplication		Without duplication	
	LB	UB	LB	UB
F_0	$\tilde{\Omega}(kF_0)$	$\tilde{O}(k(F_0 + \log n))$	–	–
l_∞	$\tilde{\Omega}(\min\{k, l_\infty\}n)$	$\tilde{O}(\min\{k, l_\infty\}n)$	–	–
degree	$\tilde{\Omega}(kd_v)$	$O(kd_v \log n)$	$\tilde{\Omega}(k)$	$O(k \log n)$
cycle-freeness	$\tilde{\Omega}(kn)$	$\tilde{O}(kn)$	$\Omega(s)$	$\tilde{O}(s)$
connectivity	$\tilde{\Omega}(kn)$	$\tilde{O}(kn)$	$\tilde{\Omega}(kr)$	$\tilde{O}(kr)$
#CC	$\tilde{\Omega}(kn)$	$\tilde{O}(kn)$	$\tilde{\Omega}(kr)$	$\tilde{O}(kr)$
bipartiteness	$\tilde{\Omega}(kn)$	$\tilde{O}(kn)$	$\tilde{\Omega}(kr)$	$\tilde{O}(kr)$
triangle-freeness	$\tilde{\Omega}(km)$	$\tilde{O}(km)$	$\Omega(m)$	$\tilde{O}(m)$

- F_0 : # distinct elements.
- l_∞ : the element with the maximum frequency.
- #CC: # connected components

All results are in terms of number of bits. Our lower bounds hold for randomized protocols with successful probability $2/3$.

For F_0 and l_∞ , n denotes the size of the universe. For graph problems, n denotes # vertices and m denotes # edges. d_v is the degree of the vertex v . Let $r = \min\{n, m/k\}$, $s = \min\{n, m\}$. $\tilde{O}, \tilde{\Omega}$ hides log factors.

What do these results imply?

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- Our lower bound for exact computation is $\Omega(kF_0/\log k)$ bits.
- We can implement a streaming algorithm for $(1 + \epsilon)$ -approximation F_0 in [Kane, Nelson, Woodruff. 2010] in the coordinator model using $O(k(\log n + 1/\epsilon^2 \log 1/\epsilon))$ bits of communication.

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- In a typical setting, we could have $\epsilon = 0.01$, $n = 10^9$ and $k = 1000$. Then $O(k(\log n + 1/\epsilon^2 \log 1/\epsilon)) = 6.6 \times 10^7$ bits, while $\Omega(kF_0/\log k) = 10^9$ bits even when $F_0 = n/100$.

Case study 2: Connectivity – the value of input layout

- Connectivity: Test if a graph is connected.

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- Connectivity: Test if a graph is connected.
- If edges are partitioned arbitrarily in the k sites **edge-partition**, we get a lower bound of $\Omega(kn / \log k)$ bits.
- If each node together with all its adjacent edges are stored in one of the k sites (**node-partition**), then we can adapt a sketching algorithm by Ahn, Guha, McGregor (2012) using $O(k + n \text{ poly log } n)$ bits.

Case study 3: Diameter – the value of approximation

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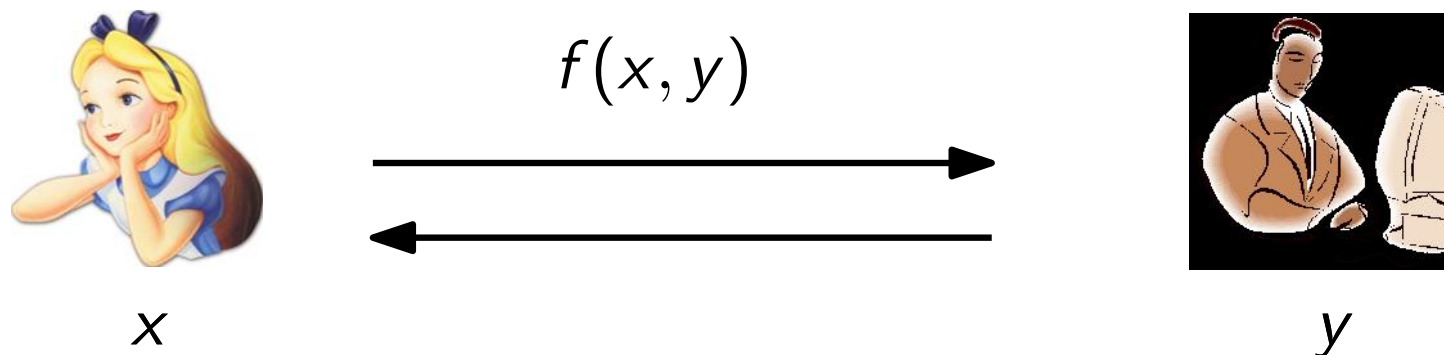
- Diameter: Compute the diameter of the graph.
- A conjecture in our paper (very recently proved by Braverman et al.): The communication cost of exact computation in the coordinator model is $\Omega(km)$ bits (allow edge duplication).
- There exists an algorithm (a distributed implementation of an algorithm Dor, Halperin, and Zwick, 2000) with cost $\tilde{O}(kn^{1.5})$ if an approximation of **additive 2** is allowed.

How to prove these results?

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Use reductions from a meta-problem THRESH
(defined later)

Basics on communication complexity



Can be easily extended to multiple players.

- R^δ : $\max_{x,y} |\Pi(x, y)|$, $|\Pi(x, y)|$ is the length of the transcript on input x, y . Π is randomized, and $\Pi(x, y) \neq f(x, y)$ w.p.r. at most δ for any (x, y) .
- D_μ^δ : $\max_{x,y} |\Pi(x, y)|$. Π is deterministic, and $\Pi(x, y) \neq f(x, y)$ for at most a δ fraction of (x, y) under distribution μ .
- ED_μ^δ : $E_{(x,y) \sim \mu} |\Pi(x, y)|$. Π is deterministic, and $\Pi(x, y) \neq f(x, y)$ for at most a δ fraction of (x, y) under distribution μ .

Easy direction of Yao's Lemma: $R^\delta(f) \geq \max_\mu D_\mu^\delta(f)$.

A direct-sum type theorem in the coordinator model

$$f : \mathcal{X} \times \mathcal{Y} \rightarrow \{0, 1\}$$

μ is a distribution over $\mathcal{X} \times \mathcal{Y}$.

$f_{\text{OR}}^k : \mathcal{X}^k \times \mathcal{Y} \rightarrow \{0, 1\}$ is the problem of computing $f(x_1, y) \vee f(x_2, y) \vee \dots \vee f(x_k, y)$ in the coordinator model, where P_i has input $x_i \in \mathcal{X}$ for each $i \in [k]$, and the coordinator has $y \in \mathcal{Y}$.

ν is a distribution on $\mathcal{X}^k \times \mathcal{Y}$: First pick $(X_1, Y) \sim \mu$, and then pick X_2, \dots, X_k from the conditional distribution $\mu \mid Y$.

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Theorem (direct-sum). For any $f : \mathcal{X} \times \mathcal{Y} \rightarrow \{0, 1\}$ and any distribution μ on $\mathcal{X} \times \mathcal{Y}$ for which $\mu(f^{-1}(1)) \leq 1/k^2$, we have $D_\nu^{1/k^3}(f_{\text{OR}}^k) = \Omega(k \cdot \text{ED}_\mu^{1/(100k^2)}(f))$. (Proof given later.)

A meta-problem: THRESH

In the THRESH_θ^n problem, site P_i ($i \in [k]$) holds an n -bit vector $x_i = \{x_{i,1}, \dots, x_{i,n}\}$, and the k sites want to compute

$$\text{THRESH}_\theta^n(x_1, \dots, x_k) = \begin{cases} 0, & \text{if } \sum_{j \in [n]} (\bigvee_{i \in [k]} x_{i,j}) \leq \theta, \\ 1, & \text{if } \sum_{j \in [n]} (\bigvee_{i \in [k]} x_{i,j}) \geq \theta + 1. \end{cases}$$

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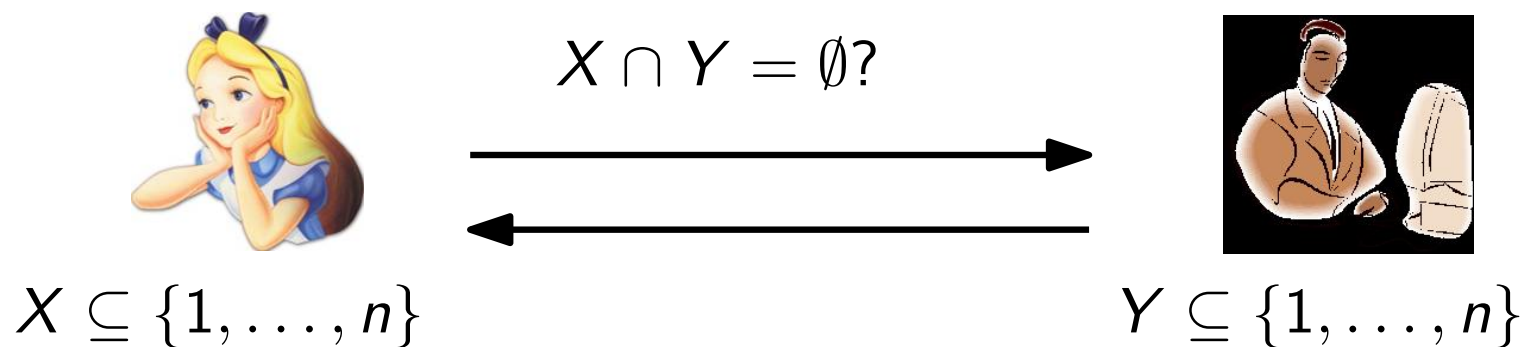
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The proof framework:

1. Choose f to be 2-DISJ with an input distribution μ , and let OR-DISJ , ν be the corresponding f_{OR}^k and its input distribution. Apply direct-sum: $D_\nu^{1/k^3}(\text{OR-DISJ}) = \Omega(k \cdot ED_\mu^{1/(100k^2)}(2\text{-DISJ}))$.
2. Show that with very high probability, $\text{OR-DISJ}(X_1, \dots, X_k, Y) = \text{THRESH}_\theta^n(X_1, \dots, X_k)$ for some θ .

2-DISJ and OR-DISJ



Exists a hard distribution τ_β , under which

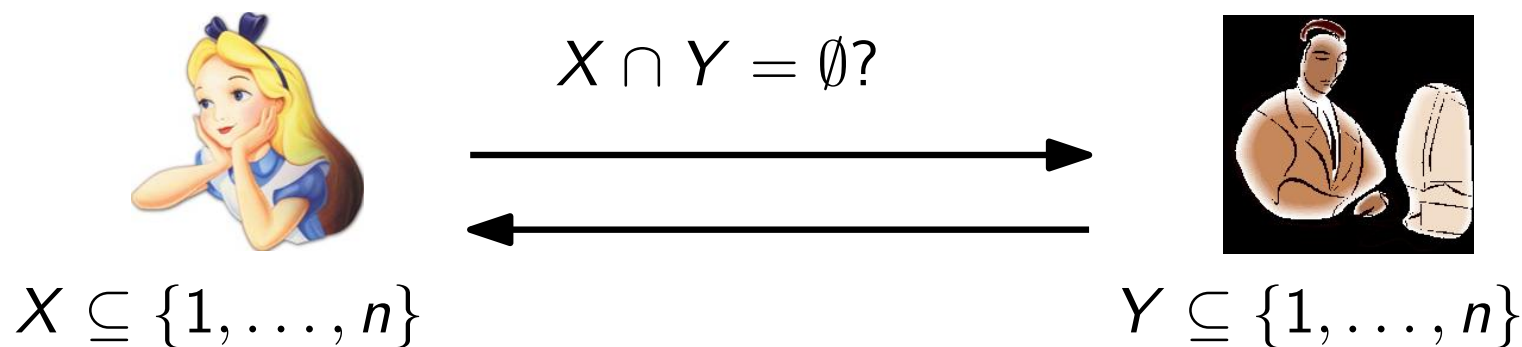
$|X \cap Y| = 1$ (YES instance) w.p. β and

$|X \cap Y| = 0$ (NO instance) w.p. $1 - \beta$.

Theorem. (Generalization of [Razborov '90, BJKS '04])

$$ED_{\tau_\beta}^{\beta/100}(2\text{-DISJ}) = \Omega(n)$$

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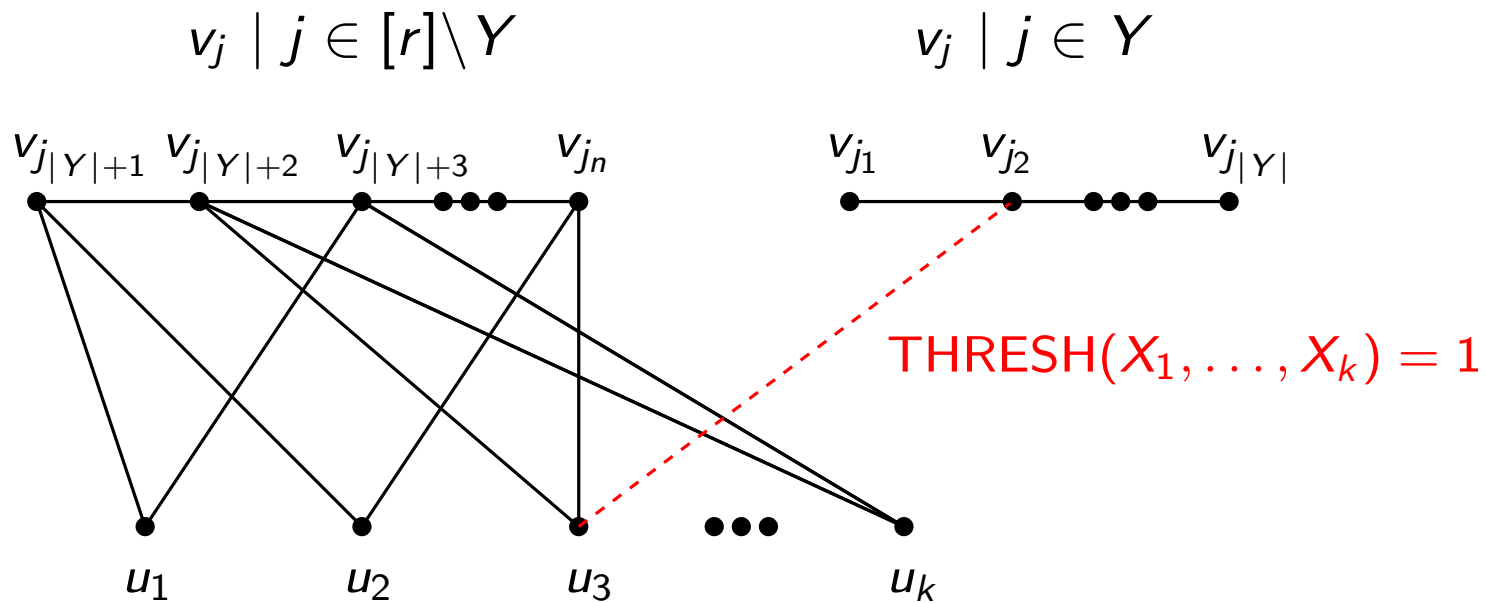
$$ED_{\tau_\beta}^{\beta/100}(2\text{-DISJ}) = \Omega(n)$$

By the direct-sum theorem, setting $\mu = \tau_\beta$ with $\beta = 1/k^2$, and ν constructed from μ , we have

$$D_\nu^{1/k^3}(\text{OR-DISJ}) = \Omega(k \cdot ED_{\tau_\beta}^{\beta/100}(2\text{-DISJ})) = \Omega(kn).$$

Example: A reduction from THRESH to Connectivity

Reduction: An input (X_1, \dots, X_k) for THRESH \Rightarrow A graph.
Each P_i creates an edge (u_i, v_j) for each $X_{i,j} = 1$. In addition, the coordinator reconstructs Y , and then creates a path containing $\{v_j \mid j \in Y\}$ and a path containing $\{v_j \mid j \in [r] \setminus Y\}$.



(u_i, v_j) exists (the graph is connected) if and only if $X_{i,j} = 1$

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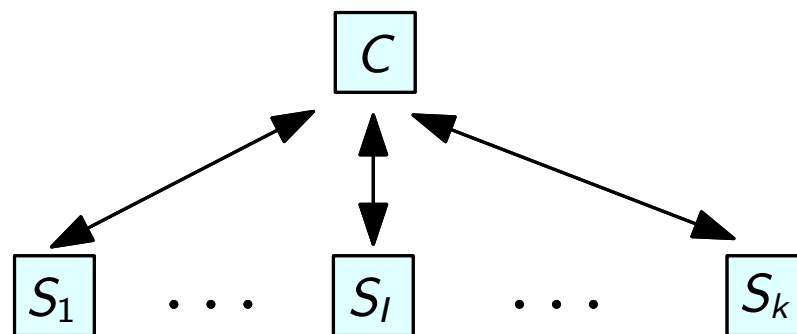
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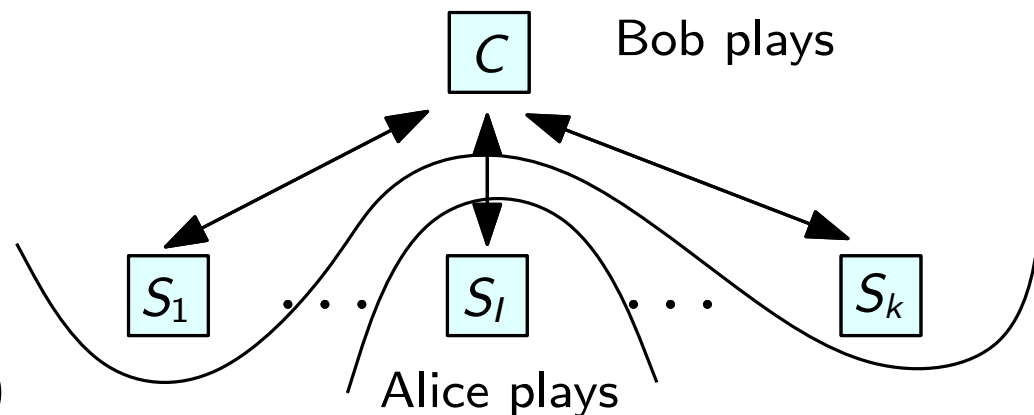
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1. Alice and Bob have input $(X, Y) \sim \mu$ ($\mu(f^{-1}(1)) \leq 1/k^2$)



2. **Input reduction:** Alice picks a **random** site S_I and assigns it with input $X_I = X$. Bob plays the coordinator C and the rest $k - 1$ sites. He assigns C with input Y , and S_i ($i \neq I$) with input $X_i \sim \mu|Y$.

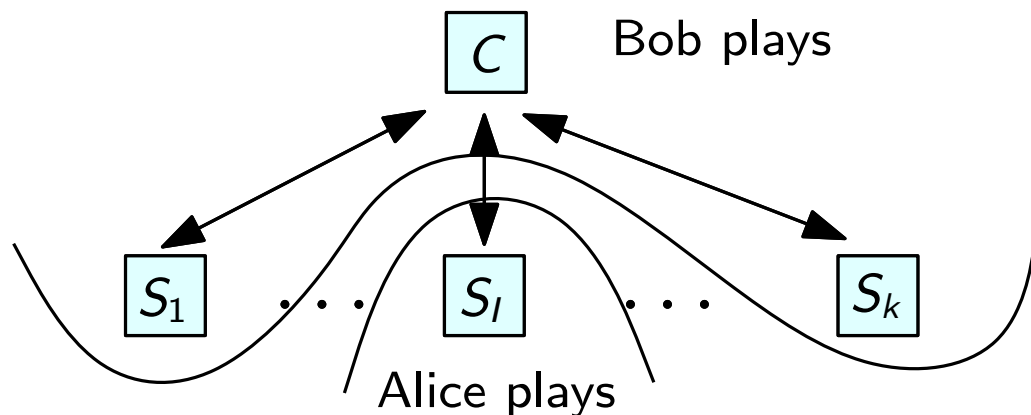
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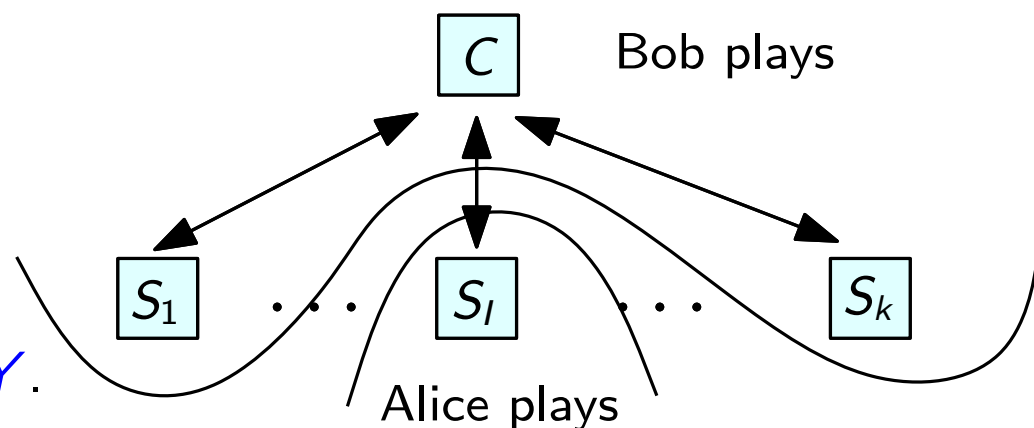
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3. They run a protocol for f_{OR}^k , w.pr. $1 - \frac{1}{k}$, $f(X_i, Y) = 0$ for all $i \neq I$, thus $f_{\text{OR}}^k(X_1, \dots, X_k, Y) = f(X_1, Y) \vee \dots \vee f(X_k, Y) = f(X_I, Y) = f(X, Y)$.

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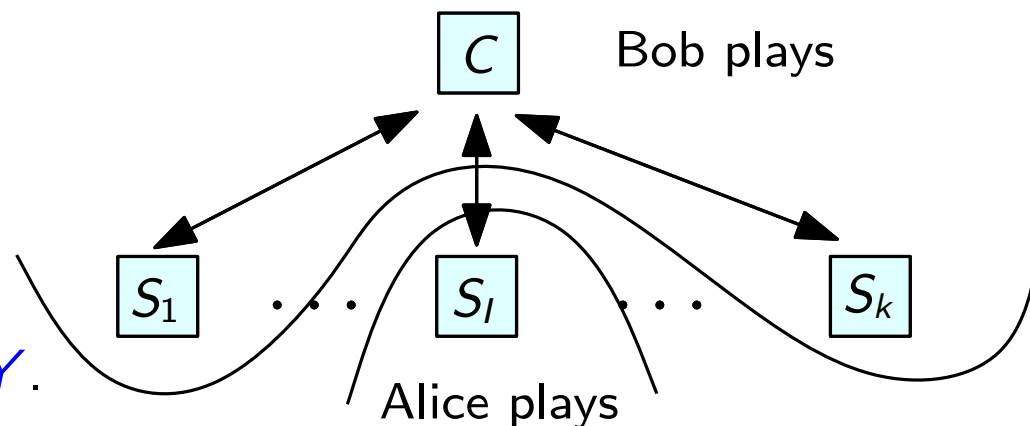
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Proof of the direct-sum theorem (cont.)

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$$\begin{aligned} & E[\text{CC}(\text{Alice}, \text{Bob})] \\ &= 1/k \cdot \text{CC}(k\text{-site problem}) \end{aligned}$$

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Conclusions and open problems

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- We attempt to deliver the following messages for protocol design in the coordinator model:
 - Allow an approximate solution.
 - Use well-designed input layouts.
 - Explore prior distributional properties of the input dataset.
- Can we obtain round-efficient protocols that (almost) match the lower bounds which hold even for round-inefficient protocols?

Our protocols for bipartiteness and (approximate) diameter require $\Omega(\Delta)$ rounds where Δ is the diameter of the graph.

Thank you!
Questions?