

Reasoning about contexts in Henkin models

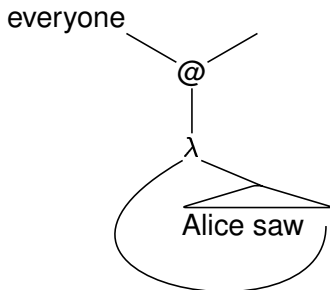
Chung-chieh Shan, Rutgers
with Chris Barker, NYU

Lambda Calculus and Formal Grammar
March 24, 2008

Contexts are syntactic functions

Alice saw [everyone].

$\text{everyone} \circ (\lambda x. \text{Alice saw } x)$



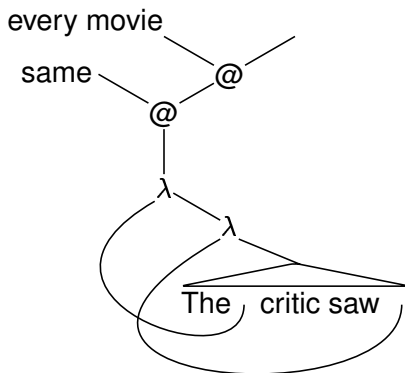
Alice saw [him].

$\text{him} \circ (\lambda x. \text{Alice saw } x)$

Contexts are syntactic functions

The [same] critic saw [every movie]. (Barker)

every movie \circ (same \circ ($\lambda x. \lambda y. \text{The } x \text{ critic saw } y$))



Americans [on average] have [2.3] children. (Kennedy & Stanley)

2.3 \circ (on average \circ ($\lambda x. \lambda y. \text{Americans } x \text{ have } y \text{ children}$))

Contexts are syntactic functions

But not 'exotic' functions such as

$\lambda x.$ if $x = \text{Bob}$
then Alice saw x
else x slept

(cf. Henkin models for higher-order logic)

Contexts are syntactic functions

But not 'exotic' functions such as

$\lambda x.$ if $x = \text{Bob}$
then Alice saw x
else x slept

(cf. Henkin models for higher-order logic)

This talk

From proof theory λ -terms and their β -equivalence

To model theory *relational* models of the λ -calculus

van Benthem 1999: Relating modal logic (categorical grammar)
and type theory (abstract categorical grammar)

NL proofs

Connectives: \ / Punctuation: •

$$\frac{\frac{\frac{}{DP \vdash DP} \quad \frac{}{S \vdash S}}{DP \bullet DP \backslash S \vdash S} \backslash L \quad \frac{}{DP \vdash DP}}{DP \bullet ((DP \backslash S) / DP \bullet DP) \vdash S} / L}{\underbrace{DP}_{\text{Alice}} \bullet \underbrace{((DP \backslash S) / DP \bullet DP)}_{\text{saw}} \underbrace{DP}_{\text{Bob}} \vdash S}$$

NL proofs

Connectives: \ / Punctuation: •

$$\frac{\frac{\frac{\overline{DP \vdash DP} \quad \overline{S \vdash S}}{\overline{DP \bullet DP \backslash S \vdash S}} \backslash L \quad \overline{DP \vdash DP}}{\overline{DP \bullet ((DP \backslash S) / DP \bullet DP) \vdash S}} / L}
 {
 \underbrace{DP}_{\text{Alice}} \bullet \underbrace{((DP \backslash S) / DP \bullet DP)}_{\text{saw}} \underbrace{DP}_{\text{Bob}} \vdash S
 }$$

$$\overline{X \vdash X}$$

$$\frac{\Gamma \vdash X \quad \Sigma[Y] \vdash Z}{\Sigma[\Gamma \bullet X \backslash Y] \vdash Z} \backslash L$$

$$\frac{X \bullet \Gamma \vdash Y}{\Gamma \vdash X \backslash Y} \backslash R$$

$$\frac{\Gamma \vdash X \quad \Sigma[X] \vdash Y}{\Sigma[\Gamma] \vdash Y}$$

$$\frac{\Sigma[Y] \vdash Z \quad \Gamma \vdash X}{\Sigma[Y/X \bullet \Gamma] \vdash Z} / L$$

$$\frac{\Gamma \bullet X \vdash Y}{\Gamma \vdash Y/X} / R$$

NL models

A *frame* consists of

- ▶ a set of points \mathcal{P} and
- ▶ a ternary accessibility relation $R_{\bullet} \subseteq \mathcal{P}^3$.

A *model* consists of a frame and a valuation \Vdash that relates points p, q, r to the structures and formulas they satisfy.

NL models

A *frame* consists of

- ▶ a set of points \mathcal{P} and
- ▶ a ternary accessibility relation $R_{\bullet} \subseteq \mathcal{P}^3$.

A *model* consists of a frame and a valuation \Vdash that relates points p, q, r to the structures and formulas they satisfy.

$$r \Vdash DP \bullet ((DP \setminus S) / DP \bullet DP)$$

$$\iff \exists p. \exists q. R_{\bullet}(p, q, r) \wedge (p \Vdash DP) \wedge (q \Vdash (DP \setminus S) / DP \bullet DP)$$

$$r \Vdash (DP \setminus S) / DP \bullet DP$$

$$\iff \exists p. \exists q. R_{\bullet}(p, q, r) \wedge (p \Vdash (DP \setminus S) / DP) \wedge (q \Vdash DP)$$

$$p \Vdash (DP \setminus S) / DP$$

$$\iff \forall q. \forall r. R_{\bullet}(p, q, r) \rightarrow (q \Vdash DP) \rightarrow (r \Vdash DP \setminus S)$$

$$q \Vdash DP \setminus S$$

$$\iff \forall p. \forall r. R_{\bullet}(p, q, r) \rightarrow (p \Vdash DP) \rightarrow (r \Vdash S)$$

NL soundness and completeness

$\Gamma \vdash X \iff$ In any model, at any point p ,
if $p \Vdash \Gamma$ then $p \Vdash X$.

The canonical completeness proof constructs a canonical model, in which points are structures.

NL_λ proofs

Connectives: \ / \ \ // Punctuation: • ◦ x λx (linear)

$$\begin{array}{c}
 \vdots \\
 \frac{DP \bullet ((DP \backslash S) / DP \bullet DP) \vdash S}{DP \circ \lambda x. (DP \bullet ((DP \backslash S) / DP \bullet x)) \vdash S} \beta \\
 \frac{\lambda x. (DP \bullet ((DP \backslash S) / DP \bullet x)) \vdash DP \backslash S \quad S \vdash S}{\lambda x. (DP \bullet ((DP \backslash S) / DP \bullet x)) \vdash DP \backslash S} \backslash R \\
 \frac{\lambda x. (DP \bullet ((DP \backslash S) / DP \bullet x)) \vdash DP \backslash S}{S // (DP \backslash S) \circ \lambda x. (DP \bullet ((DP \backslash S) / DP \bullet x)) \vdash S} // L \\
 \frac{S // (DP \backslash S) \circ \lambda x. (DP \bullet ((DP \backslash S) / DP \bullet x)) \vdash S}{DP \bullet ((DP \backslash S) / DP \bullet S // (DP \backslash S)) \vdash S} \beta \\
 \underbrace{DP}_{\text{Alice}} \bullet \underbrace{((DP \backslash S) / DP)}_{\text{saw}} \bullet \underbrace{S // (DP \backslash S)}_{\text{everyone}} \vdash S
 \end{array}$$

NL_λ proofs

Connectives: \ / \backslash // Punctuation: • ◦ *x* λ*x* (linear)

$$\begin{array}{c}
 \vdots \\
 \frac{DP \bullet ((DP \backslash S) / DP \bullet DP) \vdash S}{DP \circ \lambda x. (DP \bullet ((DP \backslash S) / DP \bullet x)) \vdash S} \beta \\
 \frac{\lambda x. (DP \bullet ((DP \backslash S) / DP \bullet x)) \vdash DP \backslash S}{S \vdash S} \backslash R \\
 \frac{\lambda x. (DP \bullet ((DP \backslash S) / DP \bullet x)) \vdash DP \backslash S}{S // (DP \backslash S) \circ \lambda x. (DP \bullet ((DP \backslash S) / DP \bullet x)) \vdash S} // L \\
 \frac{S // (DP \backslash S) \circ \lambda x. (DP \bullet ((DP \backslash S) / DP \bullet x)) \vdash S}{DP \bullet ((DP \backslash S) / DP \bullet S // (DP \backslash S)) \vdash S} \beta \\
 \underbrace{DP}_{\text{Alice}} \bullet \underbrace{((DP \backslash S) / DP)}_{\text{saw}} \bullet \underbrace{S // (DP \backslash S)}_{\text{everyone}} \vdash S
 \end{array}$$

$$\frac{\Sigma[\Gamma[\Delta]] \vdash X}{\Sigma[\Delta \circ \lambda x. \Gamma[x]] \vdash X} \beta$$

For binding, [same], and [on average], the context $\Gamma[\]$ may contain λ .

NL_λ models

A *frame* consists of

- ▶ a set of points \mathcal{P} ,
- ▶ a ternary accessibility relation $R_{\bullet} \subseteq \mathcal{P}^3$, and
- ▶ a ternary accessibility relation $R_{\circ} \subseteq \mathcal{P}^3$ (not a function),

such that there are ‘enough functions’ (more on that later).

NL_λ models: satisfaction

How to define satisfaction?

Points in structures are convenient (hybridization).

$$p \Vdash q$$

$$\iff p = q$$

$$q \Vdash \lambda x. (\text{DP} \bullet ((\text{DP} \setminus \text{S}) / \text{DP} \bullet x))$$

$$\stackrel{?}{\iff} \forall p. \forall r. R_o(p, q, r) \leftrightarrow (r \Vdash \text{DP} \bullet ((\text{DP} \setminus \text{S}) / \text{DP} \bullet p))$$

NL_λ models: satisfaction

How to define satisfaction?

Points in structures are convenient (hybridization).

$$p \Vdash q$$

$$\iff p = q$$

$$q \Vdash \lambda x. (\text{DP} \bullet ((\text{DP} \setminus \text{S}) / \text{DP} \bullet x))$$

$$\stackrel{?}{\iff} \forall p. \forall r. R_o(p, q, r) \leftrightarrow (r \Vdash \text{DP} \bullet ((\text{DP} \setminus \text{S}) / \text{DP} \bullet p))$$

But what if no point satisfies DP or no point satisfies (DP \setminus S) / DP?

$$\frac{\frac{\text{DP} \circ \lambda y. \lambda x. (y \bullet ((\text{DP} \setminus \text{S}) / \text{DP} \bullet x)) \vdash X}{\lambda x. (\text{DP} \bullet ((\text{DP} \setminus \text{S}) / \text{DP} \bullet x)) \vdash X} \beta}{(\text{DP} \setminus \text{S}) / \text{DP} \circ \lambda z. \lambda x. (\text{DP} \bullet (z \bullet x)) \vdash X} \beta$$

NL_λ models: satisfaction

The definition of satisfaction for $\lambda x. \Gamma[x]$ quantifies over the maximal substructures of $\Gamma[x]$ that do not contain x .

$$p \Vdash q$$

$$\iff p = q$$

$$q \Vdash \lambda x. (\text{DP} \bullet ((\text{DP} \setminus \text{S}) / \text{DP} \bullet x))$$

$$\iff \exists s. \exists t. (s \Vdash \text{DP}) \wedge (t \Vdash (\text{DP} \setminus \text{S}) / \text{DP}) \\ \wedge \forall p. \forall r. R_o(p, q, r) \leftrightarrow (r \Vdash s \bullet (t \bullet p))$$

Each λ -abstraction shape is like a jumbo product connective.

$$\frac{\text{DP} \circ \lambda y. \lambda x. (y \bullet ((\text{DP} \setminus \text{S}) / \text{DP} \bullet x)) \vdash X}{\lambda x. (\text{DP} \bullet ((\text{DP} \setminus \text{S}) / \text{DP} \bullet x)) \vdash X} \beta$$
$$\frac{\lambda x. (\text{DP} \bullet ((\text{DP} \setminus \text{S}) / \text{DP} \bullet x)) \vdash X}{(\text{DP} \setminus \text{S}) / \text{DP} \circ \lambda z. \lambda x. (\text{DP} \bullet (z \bullet x)) \vdash X} \beta$$

NL_λ models: the environment model condition

We require of the frame that there be ‘enough functions’:

- ▶ There must be some point q such that $q \Vdash \lambda x. x$.
- ▶ For any points s, t , there must be some point q such that $q \Vdash \lambda x. s \bullet (t \bullet x)$.
- ▶ And so on, for each λ -abstraction shape.

Or in computational terms: we can always build a closure.

NL_λ soundness and completeness

$\Gamma \vdash X \iff$ In any model, at any point p ,
if $p \Vdash \Gamma$ then $p \Vdash X$.

The canonical completeness proof constructs a canonical model, in which points are β -equivalence classes of structures.

NL_λ conservativity over NL

An NL sequent that is provable in NL_λ is already provable in NL.

Extend any NL model to an NL_λ model whose points are β -equivalence classes of structures **whose maximal substructures that do not contain variables are the old points.**

What keeps the old points separate in the new model is the confluence of the λ -calculus!

Domain theory for syntax?

Summary

Relational models of the λ -calculus

- ▶ are natural to define;
- ▶ capture the meanings of contexts as syntactic functions;
- ▶ should perhaps be equipped with kind structure.